SECTION 3 HYDRAULIC SYSTEM

Group	1 Hydraulic Circuit ·····	3-1
Group	2 Main Circuit ·····	3-2
Group	3 Pilot Circuit	3-5
Group	4 Single Operation	3-13
Group	5 Combined Operation	3-23

GROUP 1 HYDRAULIC CIRCUIT



3-1

SECTION 3 HYDRAULIC SYSTEM

50	31Q6-91220	Solenoid valve	1	Breaker
48	3106-91720	Solenoid valve	1	Q/Coupler
42	3106-20150	Pilot selector valve	1	2Vav
41	31Q6-20050	Solenoid valve	1	Cüpto Flow
40	31EM-91620	Selector valve	1	Sum)
39	31Q6-20300	Breaker pedal	1	
38	31N6-30130	Shuttle valve	2	1 Vov
37	3108-91550	Stop valve	2	2Way
36	31Q8-91680	Accumulator	1	-
35	3108-91670	Accumulator	1	
34	31Q6-20130	EPPR valve	1	
33	31N6-24130	Shuttle valve	2	
32	31Q6-90460	Shuttle valve	1	
28	31E4-11130	Pressure sensor	4	
27	31N6-25070	Last guard filter	1	
26	31N6-25060	Last guard filter	3	
25	3109-20170	Shuttle valve block	1	
24	3108-40520	Pressure sensor	7	50k
22	3108-40500	Pressure sensor	2	500k
		Accumulator	1	0.7L 15k
21	3106-20042	Solenoid valve block	1	
		Pilot fiter	1	3106-20320
20	31N8-01350	Drain filter	1	
19	31Q6-01130	Strainer	1	
10	31N4-01460	Return filter	1	
10	E131-0256	Bypass valve	1	
17	31NA-00040	Air breather	1	
16	1BQ8-40061	0il cooler	1	
15	3108-01024	Hydraulic tank	1	
14	31ER-11121	Check valve	1	3. Ok
13	31Q6-11110	Check valve	1	1. 5k
12	31Q6-40040	Turning joint	1	
11	3108-60110	Bucket cylinder	1	
10	3108-50131	Arm cylinder	1	
9	3108-50110	Boom cylinder-Right	1	
8	3108-50120	Boom cylinder-Left	1	
7	3106-20100	RCV pedal	1	
6	3108-20065	RCV lever-Right	1	
5	3108-20055	RCV lever-Left	1	
4	3808-40101	Travel motor	15	
3	3808-10151	Swing motor	1	
2	3108-17400	MCV	1	MVOO
1	3108-10010	Main pump	1	
ITEM	PARTS NO	PARTS NAME	QTY	

GROUP 2 MAIN CIRCUIT

The main hydraulic circuit consists of suction circuit, delivery circuit, return circuit and drain circuit. The hydraulic system consists of one main pump, one control valve, one swing motor, four cylinders and two travel motors.

The swash plate type variable displacement tandem axial piston pump is used as the main pump and is driven by the engine at ratio 1.0 of engine speed.

1. SUCTION AND DELIVERY CIRCUIT



The pumps receive oil from the hydraulic tank through a suction filter. The discharged oil from the pump flows into the control valve and goes out the tank ports.

The oil discharged from the main pump flows to the actuators through the control valve.

The control valve controls the hydraulic functions.

The return oil from the actuators flows to the hydraulic tank through the control valve and the oil cooler.

2. RETURN CIRCUIT



All oil from each actuator returns to the hydraulic tank through the control valve.

The bypass check valves are provided in the return circuit.

The setting pressure of bypass check valves are 1.5 kgf/cm² (21psi) and 3.0 kgf/cm² (43psi). Usually, oil returns to the hydraulic tank from the left side of control valve through oil cooler.

When oil temperature is low, viscosity becomes higher and flow resistance increases when passing through the oil cooler. The oil pressure exceeds 3.0 kgf/cm² (43psi), the oil returns directly to the hydraulic tank, resulting in the oil temperature being raised quickly at an appropriate level.

When the oil cooler is clogged, the oil returns directly to the hydraulic tank through bypass check valve (1).

The full-flow filter and bypass relief valve are provided in the hydraulic tank.

The oil from right and left side of control valve is combined and filtered by the return filter. A bypass relief valve is provided in the full-flow filter.

When the filter element is clogged, the bypass relief valve opens at 1.5 kgf/cm² (21psi) differential pressure.

3. DRAIN CIRCUIT



Besides internal leaks from the motors and main pump, the oil for lubrication circulates. These oil have to be fed to the hydraulic tank passing through spin filter and full flow filter in the hydraulic tank. When the drain oil pressure exceed 1.5 kgf/cm² (21psi), the oil returns to the hydraulic tank directly.

1) TRAVEL MOTOR DRAIN CIRCUIT

Oil leaking from the right and left travel motors comes out of the drain ports provided in the respective motor casing and join with each other. These oils pass through the turning joint and return to the hydraulic tank after being filtered by full flow filter in the hydranlic tank.

2) SWING MOTOR DRAIN CIRCUIT

Oil leaking from the swing motor come out and return to the hydraulic tank passing through a spin filter.

3) MAIN PUMP DRAIN CIRCUIT

Oil leaking from main pump come out and return to the hydraulic tank passing through spin filter.

GROUP 3 PILOT CIRCUIT



The pilot circuit consists of suction circuit, delivery circuit and return circuit.

The pilot pump is provided with relief valve, receives the oil from the hydraulic tank through the suction filter.

The discharged oil from the pilot pump flows to the remote control valve through line filter, EPPR valve, solenoid valve assemblies, swing parking brake, main control valve and safety lock solenoid valve.

1. SUCTION, DELIVERY AND RETURN CIRCUIT



The pilot pump receive oil from the hydraulic tank. The discharged oil from the pilot pump flows to the safety solenoid valve through the line filter. The oil is filtered by the line filter. The pilot relief valve is provided in the pilot pump for limiting the pilot circuit pressure.

The oil filtered by line filter flows remote control valve through safety solenoid valve.

The return oil from remote control valve returned to hydraulic tank.

2. SAFETY SOLENOID VALVE (SAFETY LEVER)



When the lever of the safety solenoid valve is moved downward, oil flows into the remote control valve through solenoid valve and line filter.

When the lever of the safety solenoid valve moved upward, oil does not flows into the remote control valve, because of blocked by the spool.

3. BOOM PRIORITY SYSTEM



When carrying out the combined operation of swing and boom up, the boom up operating speed is lowered then normal operation.

To increase working efficiency, swing speed reducing system is used.

The pilot oil from pilot pump flow into **P03** port in main control valve through boom EPPR valve. **P03** oil pressure moves swing reducing spool to upper position and oil flow rate to the swing motor decreased.

Then, the boom up speed is increased. This is called the boom priority system.

4. TRAVEL SPEED CONTROL SYSTEM



When the travel speed solenoid valve was placed in the Hi position, the pressure oil from pilot pump through line filter flows to port **Pk** of travel speed change over valve, and the control piston is pushed up, thus minimizing the displacement.

When the travel speed solenoid valve was placed in the Lo position, the oil of **Pk** port return to the tank and the control piston is returned, thus maximizing the displacement.

5. MAIN RELIEF PRESSURE CHANGE CIRCUIT



When the power max switch on the left control lever is pushed ON, the power max solenoid valve is actuated, the discharged oil from the pilot pump into Pu port of the main relief valve of main control valve; Then the setting pressure of the main control valve is raises from 350 kgf/cm² to 380 kgf/cm² for increasing the digging power. And even when press continuously, it is canceled after 8 seconds.

6. SWING PARKING BRAKE RELEASE



When one of the RCV lever (except travel lever) is tilted, the pilot oil flows into SH port through main control valve.

This pressure moves spool so, discharged oil from pilot valve flows to swing motor PG port.

This pressure is applied to swing motor disc, thus the brake is released.

When all of the RCV lever are set in the neutral position, oil in the swing motor disc cylinder is drained, thus the brake is applied.

7. SWING PRIORITY SYSTEM



When carrying out the combined operation of swing and arm of the left control valve, the swing speed can be lowered than operating speed of arm.

Pc3 pressure from the swing shuttle block change the swing priority spool and decreases the oil flow rate to the next section to make the swing operation most preferential.

This is called the swing priority system. For details, refer to page 2-45.

GROUP 4 SINGLE OPERATION

1. BOOM UP OPERATION



When the RH control lever is pulled back, the boom spools in the main control valve are moved to the up position by the pilot oil pressure from the remote control valve.

The oil from the A1 and A2 pump flows into the main control valve and then goes to the large chamber of boom cylinders.

At the same time, the oil from the small chamber of boom cylinders returns to the hydraulic oil tank through the boom spool in the main control valve. When this happens, the boom goes up.

The excessive pressure in the boom cylinder bottom end circuit is prevented by relief valve.

When the boom is up and the control lever is returned to neutral position, the circuit for the holding pressure at the bottom end of the boom cylinder is closed by the boom holding valve.

This prevents the hydraulic drift of boom cylinder.

2. BOOM DOWN OPERATION



When the RH control lever is pushed forward, the boom spools in the main control valve are moved to the down position by the pilot oil pressure from the remote control valve.

The oil from the A2 pump flows into the main control valve and then goes to the small chamber of boom cylinders. At the same time, the oil from the large chamber of boom cylinders returns to the hydraulic tank through the boom spool in the main control valve.

When the down speed of boom is faster, the oil returned from the large chamber of boom cylinder combines with the oil from the rear pump, and flows into the small chamber of the boom cylinder.

This prevents cylinder cavitation by the negative pressure when the rear pump flow can not match the boom down speed. And the excessive pressure in the boom cylinder rod end circuit is prevented by the relief valve.

3. ARM IN OPERATION



When the LH control lever is pulled back, the arm spools in the main control valve are moved to the roll in position by the pilot oil pressure from the remote control valve.

The oil from the A1 and A2 pump flows into the main control valve and then goes to the large chamber of arm cylinder.

At the same time, the oil from the small chamber of arm cylinder returns to the hydraulic oil tank through the arm spool in the main control valve. When this happens, the arm roll in.

When the roll in speed of arm is faster, the oil returned from the small chamber of arm cylinder combines with the oil from both pump, and flows into the large chamber of the arm cylinder by a make up valve.

The excessive pressure in the arm cylinder bottom end circuit is prevented by relief valve. Refer to page 3-12 for the arm regeneration.

4. ARM OUT OPERATION



When the LH control lever is pushed forward, the arm spools in the main control valve are moved to the roll out position by the pilot oil pressure from the remote control valve.

The oil from the A1 and A2 pump flows into the main control valve and then goes to the small chamber of arm cylinder. At the same time, the oil from the large chamber of arm cylinder returns to the hydraulic oil tank through the arm spool in the main control valve.

When this happens, the arm roll out. When the roll out speed of arm is faster, the oil returned from the large chamber of arm cylinder combines with the oil from both pump, and flows into the small chamber of the arm cylinder by a make up valve.

The excessive pressure in the arm cylinder rod end circuit is prevented by relief valve.

When the arm is rolled out and the control lever is returned to neutral position, the circuit for the holding pressure at the rod end of the arm cylinder is closed by the arm holding valve. This prevents the hydraulic drift of arm cylinder.

3-16

5. BUCKET IN OPERATION



When the RH control lever is manually placed in the bucket roll in position. Then the oil flows from pilot pump through the pilot valve to bucket section of the main control valve. Here the spool position is moved to bucket roll in position.

The center bypass valve is change over by the pilot pressure (Pcb) and then the oil from A2 pump is joint to the flow of A1 pump via check 1 and external piping.

The oil flows from both pump through rod end of the cylinder through the bucket section returned to the hydraulic tank.

The cavitation which will happen to the bottom of the bucket cylinder is prevented by a make up valve, on other hand. The excessive pressure is also prevented by an overload relief valve in the main control valve.

6. BUCKET OUT OPERATION



When the RH control lever is manually placed in the bucket roll out position. Then the oil flows from pilot pump through the pilot valve to bucket section of the main control valve. Here the spool position is moved to bucket roll out position.

The oil flows from A2 pump through bucket section of main control valve to the rod end of the bucket cylinder, and to roll out bucket.

The return oil flows from the bottom end of the cylinder through the bucket section returned to the hydraulic tank.

The cavitation which will happen to the rod of the bucket cylinder is prevented by a make up valve, on other hand. The excessive pressure is also prevented by an overload relief valve in the main control valve.

7. SWING OPERATION



When the LH control lever is manually placed in the left (right) swing position. Then the oil flows from A1 pump through the swing section of the main control valve to swing motor to left (right) swing the superstructure. The return oil flows from swing motor through the swing section of the main control valve returned to the tank.

When the control lever placed in the neutral position, the pressure of the pilot oil passage down.

Then the brake release valve returned to the neutral position and the oil is returned from the brake piston to the tank. And the brake is set to "ON". The swing parking brake, make up valve and the overload relief valve are provide in the swing motors. The cavitation which will happen to the swing motor is prevented by the make up valve in the swing motor itself.

SWING CIRCUIT OPERATION



1) MOTOR BRAKE VALVE

Motor brake valve for the swing motor limits to cushion the starting and stopping pressure of swing operation.

2) MAKE UP VALVE

The make up valves prevent cavitation by supplying return oil to the vacuum side of the motor.

3) PARKING BRAKE

In case that the parking, of the machine at slope is required during operation, there is the danger of involuntary swing caused by the self weight of the machine. The brake is connected to prevent this involuntary swing.

PARKING BRAKE "OFF" OPERATION

The parking brake is released by the pilot pressure oil from the pilot pump.

When the left control lever placed in the swing position, the pilot pressure at the shuttle valve is transferred to the brake release valve and the brake release valve is change over. Then the pilot pressure lift the brake piston and release the parking brake.

PARKING BRAKE "ON" OPERATION

When the control lever placed in the neutral position, the pressure of the pilot oil passage down. Then the brake release valve returned to the neutral position and the oil is returned from the brake piston to the tank. And the brake is set to 'ON".

4) BYPASS VALVE

This bypass valve absorbs shocks produced as swing motion stops and reduced oscillation cause by swing motion.

8. TRAVEL FORWARD AND REVERSE OPERATION



When the right and left travel levers are manually placed to the forward or reverse position, the oil flows from pilot pump through the pilot valve to travel sections of the main control valve.

Here, spool position is moved to forward and reverse position. The oil flows from A2 pump through the travel (RH) section of the main control valve and turning joint to the right travel motor and oil flows from A1 pump through the travel (LH) section of the main control valve and turning joint to the left travel motor and move the machine forward or reverse.

The return oil flows from both travel motor through the turning joint and travel (RH, LH) sections returned to the tank.

TRAVEL CIRCUIT OPERATION

TO/FROM MAIN CONTROL VALVE

Valves are provided on travel motors to offer the following functions.

1) COUNTER BALANCE VALVE

When stopping the motor of slope descending, this valve to prevent the motor over run.

2) OVERLOAD RELIEF VALVE

Relief valve limit the circuit pressure below 380 kgf/cm² to prevent high pressure generated at a time of stopping the machine. Stopping the motor, this valve sucks the oil from lower pressure passage for preventing the negative pressure and the cavitation of the motor.

GROUP 5 COMBINED OPERATION

1. OUTLINE

The oil from the A1 and A2 pump flows through the neutral oil passage, bypass oil passage and confluence oil passage in the main control valve. Then the oil goes to each actuator and operates them. Check valves and orifices are located on these oil passage in the main control valve. These control the oil from the main pumps so as to correspond to the operation of each actuator and smooth the combined operation.

STRAIGHT TRAVEL SPOOL

This straight travel spool is provided in the main control valve.

If any actuator is operated when traveling, the straight travel spool is pushed to the right by the pilot oil pressure from the pilot pump.

Consequently, the left and right travel oil supply passage are connected, and equivalent amount of oil flows into the left and right travel motors. This keeps the straight travel.

2. COMBINED SWING AND BOOM UP OPERATION

When the swing and boom up functions are operated, simultaneously the swing spool and boom spools changed. The oil flows from the A2 pump through boom1 section of the main control valve to boom cylinders and the boom functions.

The oil flows from A1 pump flow into swing motor through swing spool and the boom cylinder through boom 2 spool.

The upper structure swing and the boom is up.

Refer to page 3-8 for the boom priority system.

3. COMBINED SWING AND ARM OPERATION

When the swing and arm functions are operated, simultaneously the swing spool and arm spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve.

The oil from the A1 pump flows into the swing motor through swing spool and the arm cylinder through arm 1 spool.

The oil from the A2 pump flows into the arm cylinder through the arm 2 spool of the right control valve. The upper structure swings and the arm is operated.

4. COMBINED SWING AND BUCKET OPERATION

When the swing and bucket functions are operated, the swing and bucket spools changed. The oil flows from the A2 pump through the bucket section of the main control valve to the bucket cylinder and the bucket functions. The oil flows from A1 pump through swing section of the main control valve to the swing motor and swing the superstructure.

5. COMBINED SWING AND TRAVEL OPERATION

When the swing and travel functions are operated, simultaneously the swing spool and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve. At the same time, the straight travel spool is pushed to the right by the pilot oil pressure from the pilot pump.

The oil from the A2 pump flows into the swing motor through the swing spool. The oil from the A1 pump flows into the travel motor through the RH travel spool of the right control valve and the LH travel spool of the left control valve via the straight travel spool.

The superstructure swings and the machine travels straight.

6. COMBINED BOOM AND TRAVEL OPERATION

When the boom and travel functions are operated, simultaneously the boom spools and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve. At the same time, the straight travel spool is pushed to the right by the pilot oil pressure from the pilot pump. The oil from the A2 pump flows into the boom cylinders through the boom 2 spool and boom 1 spool via the parallel and confluence passage in case boom up operation. The oil from the A1 pump flows into the travel motors through the RH travel spool of the right control valve and the LH travel spool of the left control valve via the straight travel spool.

7. COMBINED ARM AND TRAVEL OPERATION

When the arm and travel functions are operated, simultaneously the arm spools and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve. At the same time, the straight travel spool is pushed to the right by the pilot oil pressure from the pilot pump. The oil from the A2 pump flows into the arm cylinders through the arm 1 spool and arm 2 spool via the parallel and confluence oil passage. The oil from the A1 pump flows into the travel motors through the RH travel spool of the right control valve and the LH travel spool of the left control valve via the straight travel spool.

8. COMBINED BUCKET AND TRAVEL OPERATION

When the bucket and travel functions are operated, simultaneously the bucket spool and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve. At the same time, the straight travel spool is pushed to the right by the pilot oil pressure from the pilot pump. The oil from the A2 pump flows into the bucket cylinder through the bucket spool via the confluence oil passage. The oil from the A1 pump flows into the travel motors through the RH travel spool of the right control valve and the LH travel spool of the left control valve via the straight travel spool of the control valve.